Shubham Kumar

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📞 07024360666   📅 21/12/2000

in Linkedin   ↖ Portfolio

EDUCATION

B.Tech (Chemical Engineering), *Rajiv Gandhi Institute Of Petroleum Technology*
2017 – 2022 | Jais, India

Upraised - Career Accelerator Program
08/2022 – 12/2022

SKILLS

- Figma
- Mixpanel
- Powerpoint
- Excel
- Word
- Whimsical
- Sketch
- Google Analytics
- SQL

LANGUAGES

English

Hindi

ACHIEVEMENTS

IIT MAINS (2017) and IIT JEE ADVANCE (2017)

PROFILE

A product enthusiast eager to solve 'What,Why,How' for Organizations and Products. I thrive in a fast paced environment and love taking on challenges.

PROFESSIONAL EXPERIENCE

Upraised - Product Management Fellowship - CAP
08/2022 – present
Portfolio ↗
- Creating PRD's Reports Upon Building and Improving the Existing Products/Company.
- Understanding problem solving techniques to find Metrics and RCA and building and improving products.
- Building wireframes for Designers.

Product Requirements Documents

PRD - Book My Dr. ↗
To ease the daily operations of Clinic / Hospitals by Advance Booking of checkup appointments with a Specific Doctor and all other (X-Ray, Sonography Etc.) services provided by the Hospitals.

PRD - Upraised ↗
Upgrading student adept skills through specialized training by improving content and process of selection - Entering new market

PRD - Lyft's ↗
Maximising Lyft's profits

PRD - Unstop ↗
Increasing users acqusition by introducing new referral system at unstop.

PRD - Gpay ↗
Product Strategy for Gpay

UI/UX Design

UI/UX - Book My Dr. ↗
Product Design - Gpay ↗

PROJECTS

Autonomous Quadcopter / Drone
- Using APM ADURINO flight controller board with GPS location tracking , Obstacle avoiding LIDAR / SONAR Sensor , FPV camera, Long range communication via telemetry , 4 x 25000 RPM Brushless Motors
- Drone can trace a pre-decided path/course that has been set on software using setting a latitude and longitude of every point and connecting them for a path.
- Drone can avoid obstacles by emitting infrared light or ultrasonic sound to detect its surroundings and locate the position of obstacles to avoid them.